

Silent Talker: A New Computer-Based System for the Analysis of Facial Cues to
Deception

Silent Talker

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Summary

This paper presents the development of a computerised, non-invasive psychological profiling system, 'Silent Talker', for the analysis of nonverbal behaviour. Nonverbal signals hold rich information about mental, behavioural and/or physical states.

Previous attempts to extract individual signals and to classify an overall behaviour have been time-consuming, costly, biased, error-prone and complex. Silent Talker overcomes these problems by the use of Artificial Neural Networks. The testing and validation of the system was undertaken by detecting processes associated with "deception" and "truth". In a simulated theft scenario thirty-nine participants 'stole' (or didn't) money, and were interviewed about its location. Silent Talker was able to detect different behaviour patterns indicative of "deception" and "truth" significantly above chance. For example, when 15 European men had no prior knowledge of the exact questions, 74% of individual responses ($p < .001$) and 80% ($p = .035$) of interviews were classified correctly.

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There is a long history of research in the field of nonverbal behaviour.

Nonverbal cues have, with some difficulty and extensive effort, been collected and analysed by humans. In spite of the many problems this has posed, little work has been carried out on the use of machines for the collection and analysis of these cues. A system that is able to non-invasively, quickly and simultaneously analyse many nonverbal cues and their interrelationships has long been needed. This paper describes such a system and its implementation/testing. *Silent Talker* is an Artificial Neural Network-based system that automatically collects and analyses nonverbal cues to classify an overall behavioural/psychological state. It can be adapted to detect different such states and tuned to particular situations, environments and applications. In this paper the determination of a particular state is described as *profiling*.

Nonverbal behaviour consists of all the signs and signals--visual, audio, tactile and chemical--used by human beings to express themselves, except speech or manual sign language (Scherer and Ekman, 1982). These cues hold rich information about mental, behavioural and/or physical states and are, at least in part, involuntary and unintended. Physiological cues, such as EEG waveforms, also hold information, but these generally require invasive contact. The work presented in this paper is limited to visible nonverbal behaviour, but could easily be extended to include physiological measurements, other nonverbal behaviour, e.g. voice pitch, and verbal behaviour such as the number of self-references (Zuckerman and Driver, 1985).

We use the term *channel* to describe behaviour at a finer level of granularity than is normally used in the deception literature. Each channel is an attribute being measured, such as an eye contact event, gaze direction or body movement. The total

nonverbal behaviour exhibited is *multichannel*, many channels representing the overall psychological state of a subject (Scherer and Ekman, 1982). A channel is affected by level of control over that channel, level of arousal/felt, emotion and cognitive processing demands (Zuckerman and Driver, 1985). People may try to control their postures, movements and gestures to convey a message not in accordance with their true feelings, but it is unlikely that nonverbal behaviour can be faked completely, because of the probable lack of congruence between numbers of channels (Pease, 1984).

A typical hallmark of much nonverbal analysis is a fine-grain temporal analysis first expounded by Efron (1941). In this methodology, a judge observes and codes channel data for each frame of a video. This may simply be a note of whether a particular behaviour is taking place, a measure of duration over a number of frames, or a subjective opinion (Scherer and Ekman, 1982). For multichannels, observation and coding is performed a number of times, once for each channel. Coding may be repeated by a number of judges to avoid bias by an individual judge. The multichannel codes are analysed over multiple frame groupings.

It may take one hour to code (or *extract*) a particular channel from one minute of videotape (Johnson, 1999). Once the coding of multichannels is complete, the subsequent analysis over multiple frame groupings is often complex and time consuming, due to the high dimensionality possible. Thus, important patterns in the data may be missed and the result of the analysis may be costly, incomplete and too late to be useful. Vrij, Evans, Akehurst, and Mann (2004) have shown that it is possible for humans to use rapid judgements in assessing verbal and nonverbal channels in order to detect processes related to truth and deceit. However, the judges have to be trained, can concentrate upon only a limited number of channels at one

time and can be biased or make errors due to fatigue, for example. Also, relevant channels and patterns between channels may be unwittingly ignored.

There are electronic machines able to measure physiological or behavioural variables that may subsequently be interpreted as correlated with a psychological state. Many require the additional subjective opinion of a judge and/or some base-line measurements. Such machines are limited in scope because only one psychological state is measured; they are also limited in ability because only a small number of fixed channels are used for cost and analysis reasons, resulting in the possibility of measuring behaviour other than that desired, or providing insufficient data for classification. Also, it is more likely that a subject could control a small number of channels in order to convey a message that is not in accordance with their true feelings. Where a judge and base-line measures are introduced there is an element of bias. A well-known machine of this type, designed to detect “deception”, is the Polygraph. This machine has been the subject of many studies; relatively recent ones include Lykken, 1998; Olsen, Harris, Capps and Ansley, 1997; Vrij, 2000. There are two popular types of test, *guilty-knowledge* and *control-question*. The former can be used in only limited circumstances whilst the latter involves base-line measures. For a description of the tests and typical results, see Vrij, 2000. A trained judge uses the channel data recorded by the Polygraph along with his or her own perceptions of the subject in order to make a final assessment. The judge’s assessment may have an element of bias; further, the three Polygraph channels all measure arousal, and a subject may have learnt to control the limited number of channels (Vrij, 2000; Williams, 2001).

Research into manual, electronic and computer-based systems has also concentrated upon the use of a small number of channels, a simple combination of

those channels, sometimes relying upon channels that monitor occasional, discrete events such as *microexpressions* or *false smiles*. A microexpression is a short-lived, unexpected expression and a false smile is one which does not involve eye movement (Ekman, 1985). Pavidis, Eberhardt, and Levine (2002) use a computer to detect blood-flow under the eyes (single channel) in order to determine “deception”. Bartlett et al (1999) use a computer system to automatically recognise facial actions and thus detect a fleeting microexpression and/or the presence of a false smile in order to determine “deception”. Ekman (1988) combines false smiles (detected by a judge) and one vocal measure to determine “deception”. Cohn and Katz (1998) combine facial muscle movements (measured invasively) with four vocal measures to determine “negative”, “neutral” and “positive” emotion.

Iwano, Sukegawa, Kasahara, and Shirai, (1995) use a larger number of channels and look for closeness between a response pattern and a *typical* pattern. A computer is used to extract a number of facial distances from a roughly stationary head. These are combined with two vocal channels in an attempt to determine “agreement”, “denial”, “unexpected”, “withhold”, and “dislike”. They calculate a typical pattern for each of the behaviours by looking at each response from all the participants. The patterns may be quite simple, e.g. a nod and raised pitch indicating “agreement”. They compare each response pattern to the typical patterns testing only people who had been used to create the typical patterns. For complex behaviours such as deception, there may not be a single typical pattern but a number of patterns that could represent a given behaviour.

The systems discussed above are costly, complex, time-consuming, and/or error-prone. Some use too few channels, or a simple combination/analysis of channels; some rely upon channels that monitor occasional discrete events or are

limited in scope and/or ability; others are not fully automatic and are biased where a base-line or the subjective opinion of a judge is required.

The use of Artificial Neural Networks (Hassoun, 1995) offers a way of overcoming these problems. An Artificial Neural Network (ANN) is a non-linear statistical model. ANNs can be trained to perform tasks (such as classification of inputs to the network), by presenting them with a training set of sample cases and the desired classifications, represented in a numerical form. The learning takes place by the modification of numerical weights on the connections between the artificial neurons. ANNs learn features or principles of classification, and thus can classify unseen cases.

ANNs have been used for many diverse applications. In this work ‘liars’ and ‘truth tellers’ are video recorded. ANNs detect body movements in order to instantly measure the occurrence of many specific behaviours, such as eye blinks and sideways head movements. ANNs then classify the behavioural patterns as processes related to “deception” and “truth”.

Detecting processes related to “deception” and “truth” is a difficult task because non-verbal deceptive behaviour depends upon the participant, the context/situation, the characteristics of the lie and the person trying to detect the lie (Ekman, 1985). Thus, there are many variables to consider. These include motivation (high, medium, low), planning (spontaneous, planned, practised), participant (gender, ethnicity/culture, age) and interviewer (gender, culture, age, status, respect of, common values with, familiarity, level of suspicion) (Bond, 1990; Burgoon, Buller, Grandpre, and Kalbfleisch, 1998; Ekman, 1985; Ekman, 1988; Pavidis et al., 2002; Porter, Woodworth, and Birt, 2000; Vrij, 1994; Vrij, 2000; Vrij and Semin, 1996; Zuckerman and Driver, 1985). In addition, the same participant and same event may

produce a different set of responses at a different time due to the physical setting, recent influences or experience by that participant. At any one time, a response may not be fully deceptive or truthful, but some blend of truth and lie.

It is desirable that the responses analysed are of the types that occur in real-life contexts. For example, a natural conversation, which draws out a participant's description of an event, contains more information than a rigid set of closed questions that elicits a "yes" or "no" response.

Method

Participants

In order to provide training and testing data for the system a number of interviews were recorded. The interview collection strategy was adapted from Vrij, (1994), where the detection of deception was the phenomenon under scrutiny. Thirty-nine adult volunteers (age range 20 to 50) performed small tasks and were interviewed about them. The participants were students, academic and other staff from the University's Department of Computing and Mathematics. Approximately half were male; two-thirds of both genders were of European origin. None had specific knowledge of cues related to truth and deception.

The interviews took place over a number of days. Participants were instructed not to convey details of the interviews to each other. In addition, participants well-known to one another were filmed on the same day. There was no manipulation of the lighting or of the participants' appearance or movements.

Data Collection

On arriving, each volunteer was issued with a random number and an information sheet which included the reasons for the study and some information

designed to improve their motivation to lie, i.e. text informing them that deception was often called upon for positive reasons and was a skill they might need to put into practice in the workplace. This trial did not use a financial incentive. The participants volunteered on the basis that they were making a useful contribution to scientific knowledge.

On entering the interview room alone, the participant found an instruction sheet. This asked the participant to take a box from under the chair and inspect its contents. The box contained a pair of spectacles and a ten-pound note. If the participant had an odd number, the participant was required to pocket the money (task A). An even number required the participant to replace the money in the box (task B). The box was to be put back under the chair. Participants read that they were about to be interviewed about the location of the money and that they would be accused of taking it. Participants having the money in their pocket were instructed not to admit this. A few minutes later, the interviewer arrived. After a brief greeting, the interviewer asked ten ordered questions in a consistent manner.

Q1 I know that you've looked in the box. Please tell me what you saw.

Q2 How much money was in the box?

Q3 What did you do with the money?

Q4 Are you sure that you didn't take the money from the box?

Q5 Have you any pockets?

Q6 When did you last use your pockets?

Q7 Did you put the money in your pockets?

Q8 Please describe the contents of your pockets.

Q9 Are you telling the truth about the location of the money?

Q10 Have you lied in this interview?

During the interviews, the interviewer did not know whether a volunteer was lying or telling the truth. Later, the interviewee performed the task that he/she had not performed earlier, and a second interview was undertaken. Identical questions to the first interview, in identical order, were asked. In a truthful interview all ten questions produced truthful responses. In a deceptive interview many of the questions produced deceptive responses. However, Q5 produced a truthful response because all the participants had pockets, and Q1 and Q2 produced usually truthful responses because most participants admitted that they had looked in the box. The mean interview length, from the beginning of the response to Q1 to the end of the response to Q10, was 59 seconds ($SD=15$ seconds).

For the purposes of this work we define an unplanned interview as one in which the participant has been asked a set of questions for the first time and with no prior indication of what is to be asked. A planned interview is one in which the participant goes through an exact repetition of the unplanned interview a short time afterwards. It is reasonable to believe that some of the questions and their order of occurrence in an initial interview of this type would not be anticipated. Furthermore, the second interviews do simulate real-world processes involving a series of interviews over extended time in which questions are repeated to check for consistency. Consequently, the trials do bear some similarity to real-world interviews.

For each interview, three cameras were used to record full body, head and shoulders, and head and torso. For purely operational purposes an operator was required to start and stop the cameras and establish synchronisation. For some people the presence of the camera operator may have increased their duping delight or embarrassment (Vrij, 2000). To control this, the operator entered the room just before the interviewer, avoided eye contact throughout the interview and then left the room

just after the interviewer. In a fully-developed system there would not be any need for a camera operator, the camera would be connected directly to the computer, and camera data processed in real-time by the computer. However, for this initial work, the interviews were recorded on to SVHS tapes, which were later digitised. This allowed for the collection of ANN training data and for slightly different training/testing scenarios.

After the two interviews, a de-briefing sheet was completed, asking for the participant's consent for the videos to be used, and details about when and where they deceived. The 39 people yielded 78 useable interviews each containing 10 questions. These provided 774 individual responses; 6 responses were lost due to interviewer error. Half of the interviews contained *unplanned* responses (1st interview) and half contain *planned* responses (2nd interview). Half of the interviews were *deceptive* and contained some responses that were deceptive and some that were truthful. The other interviews were *truthful* and contained only truthful responses.

The interviewee's head and shoulder images were used. Each video was digitised into a 15 frames-per-second Audio–Video Interleaved (AVI) file. A response was deemed to start one second before interviewees started talking and end two seconds after they stopped talking. Using this criterion the mean response length was 6 seconds ($SD=3$ seconds). A response *overlap* sometimes occurred if the interviewer asked a question in less than three seconds.

Head and Shoulder Video Choice

In the detection of “deception” both body and face leak deception cues (Ekman, 1985; Ekman, O'Sullivan, Friesen, and Scherer, 1991). It was decided to concentrate initially upon images from the interviewee's head and shoulder videos. In day-to-day encounters much non-verbal communication is expressed using the face,

with some or all of the lower part of the body hidden – for example, by posture. Although the face can mislead the untrained eye because it is best equipped to lie, it can also leak the most cues (Ekman, 1997). Whilst many can only detect deception to chance levels (Zuckerman and Driver, 1985), some, who have difficulty in understanding speech due to brain damage, have been able to detect deception to 73% in silent head and shoulder videos (Ectoff, Ekman, Magee, and Frank, 2000). Experiments using individual channels from head and shoulder videos have given contradictory results (Zuckerman and Driver, 1985; Ekman, 1985) but, in light of the results from brain damaged people, our hypothesis was that channel interrelationships, rather than individual channels, would prove important.

Theme and Channel Choice

In many circumstances known data can help the detection process. Since there are differences in non-verbal behaviours between men and women and persons of different race (Bond, 1990; Vrij, 2000), those chosen in this study were *gender*, *race* and *planning*, the last with reference to the planned/unplanned interviews.

In this work the head and shoulder images were used and channels were based upon the face and head. An overview of previous work by Zuckerman and Driver (1985) showed that researchers investigating deceptive behaviours considered a number of visible channels based upon the face and head: pupil dilation, gaze, blinking, smiling, facial segmentation and head movements. No single channel emerged as the most sensitive source. In this work the four *themes* chosen were *eye gaze*, *eye closure*, *face/head movement* and *blushing/blanching*. Each theme contains a number of channel values. A fifth theme comprised the *known data* items *gender*, *race* and *planning*, and for the purpose of simplicity, these are also referenced as

channels. In total 24 channels were used (Table 1). The rationale for theme/channel choice is given below.

The eye gaze theme was considered because folk-wisdom says that a person avoiding eye contact is embarrassed, hiding something or concentrating. However, both liars and truthful people may control their gaze in an attempt to appear honest. The eye closure theme was considered in order to monitor blinking, closing the eyes for a longer period, and looking down. Blinking is mostly linked to arousal, but to a lesser extent it may be controlled, or affected by cognitive processing events. Cognitive processing due to concentration or daydreaming, for example, could delay a blink as a person “stares into space”. A person looking down, or closing their eyes for a short period, may also indicate cognitive processing or avoidance.

The head movement theme was considered because such movement may be used to illustrate a point, or to indicate yes and no responses. Cognitive processing automatically causes a decrease in movement (Vrij and Semin, 1996). Although gross head movements may be controlled, small head movements are less likely to be controlled, and strong emotions may cause sudden jerky or shaky movements. The blushing and blanching theme was considered because these are likely to be affected by the emotions, cognitive processing demands, or possibly control. Blushing and blanching was one of two indicators suggested by Ekman (1985); the other was downward gaze.

Pupil dilation was not considered in this work because small changes in light levels affect the size of the pupil more than cognitive processing or arousal (Janisse, 1977). If the pupil size is to be valid data, the gaze direction must be limited or the light levels at the position of gaze must be measured. The former would hinder the natural movement of the subject. The latter would require the interview area to be

restrictive and contain much specialised measurement equipment. The smile was not considered because of mouth movement entailed in answering. Nonetheless, smile, mouth movement and facial segmentation could be the subject of further study.

The System

Figure 1 shows the working arrangement of a trained and tested system. The system has been developed using a camera and laptop computer but dedicated hardware could be utilised. The camera and computer are initialised. The interview starts. The camera passes video frames of the interviewee to the computer (currently to videotape which is digitised and then to the computer), which uses ANNs to track body parts, extract channel data over time and to analyse patterns across channels. The computer displays a classification to the interviewer.

Figure 2 shows a diagram of the system (described more fully in the International Patent Number WO02087443 (2002)). Sections A (video camera) to C (pattern detectors) are concerned with locating and examining the status of a number of important channels, e.g. locating an eye and determining if it is closed. Sections D and E refine and consolidate this data into a single stream which is used for classification. Sets of ANNs are used in the location, detection and classification stages. The procedure, from object location to classification, is said to be operating in *near real-time*. This means that the system can process data fast enough to give classifications of truth or deception on a question-by-question basis during an interview. This definition differs from a narrower definition of real-time operation used in computing and engineering.

Implementation

Classification of a participant's behaviour in responding to questions requires the development of ANNs for identifying visible features (object location),

deformation of particular visible features (pattern detection) and, finally, classification of the consolidated data collected over the response. This paper describes basic methods for developing these ANNs; full details of useable topologies, learning algorithms and parameters are in previous work (Hassoun, 1995; Rothwell, 2002).

The classic development methodology for classifier ANNs is to take a data set for the domain in question and divide it into a training set and a test set, which are mutually exclusive. The ANN is trained on the training set until some predefined stopping criterion is met, then the ANN is used to classify the test set and the percentage classification accuracy is used as the measure of success. A suitable ANN would then be deployed to perform classifications in a real-world application. Refinements to this procedure are well-known and accepted by the ANN community. It is now considered to be good practice to partition the training data into the training set and an additional validation set. The training then takes place in phases. At the end of each phase the validation set (not seen during training) is classified and the classification accuracy measured. The stopping criterion then becomes the point at which the classification accuracy for the validation set stops improving.

When the data set is small, the partitioning just described leaves too small a training set for effective learning by the ANN. Researchers have adopted the n-fold cross-validation technique to deal with this (Stone, 1974). Here the data is randomly divided into n subsets. One subset is reserved for testing and the remaining n - 1 are used for training. The role of the test set is rotated through the n subsets and the n results are averaged to give the overall classification accuracy. In this study we combine the validation set with n-fold cross validation.

Training starts by initialising the random connection weights, in the range -1 to 1 . The training runs are repeated a number of times with different starting seed

values. This avoids the training of the ANN being stalled at a sub-optimal level of performance (Hassoun, 1985). Classification accuracy of the validation set is also used to choose a single ANN from a set of ANNs having different seeds (different random starting weights).

Object locator ANNs

Each object locator specialises in a visible feature such as a face, eye, eyebrow or nose. The development of the face locator provides a good representation of the object locators as a whole. In this study, face and non-face images were collected from the training video frames. The face images were cropped to the eye and nose area; non-face images were collected randomly from appropriate areas of the frame. The images were standardised using a set of well-known techniques (Kung, Fang, Chui, and Taur, 1995; Lin, Kung, and Lin, 1997; Rae and Ritter, 1998; Rothwell, 2002; Swets and Weng, 1996). The result was a numeric pattern (vector) suitable for input to an ANN. The ANNs can learn to cope with distractions such as makeup, glasses, and facial hair.

Table 2 contains training and testing details for each *object locator* -face, left eye, left eyebrow and nose: the right-handed features being treated as mirror-images of their left-hand equivalents. In each case, half of the objects and non-objects were used for training, and the others used for testing purposes. For each test image the ANN output was compared to a manual classification. The Classification Accuracies are the percentage of *objects* classified correctly by the ANN, the percentage of *non-objects* images classified correctly and the overall *total* percentage of object and non-object images classified correctly.

Pattern detector ANNs

A similar procedure was adopted for the pattern detectors, which detect changes in state of the objects. Training and testing details for these are given in Table 3. For example, images of the left eye were collected from the training data video frames. These were labelled as one of two classes – the first being the eye fully closed (target pattern), the second being all other states of openness of the eye (non-target patterns). This data was then partitioned into training and test sets for the *eye closed* classifier ANN.

Channel coding

Three of the channels are static attributes of the participant. The remaining 21 are derived from the video frames. The data from these 21 channels is consolidated over a certain time period and concatenated to the first 3 to form the input of the ANN which acts as the behaviour classifier. The inputs to the ANN are real-valued in the range -1 to 1 . Of the 774 useful individual responses to questions, 688 produced valid channel data when passed through the object location and pattern detection stages. The remaining responses were rejected due to the channel outputs being *invalid*. This may have occurred, for example, because a particular object was not located for the requisite time (at least 90% of the response time).

Training and Testing Results

Half of the interviews were truthful and contained 10 truthful (tt) responses. The other interviews were deceptive and contained 7 deceptive (dd) and 3 truthful (td) responses. In real-life situations it is likely that someone deceiving will tell the truth some of the time. People telling the truth in a deceptive interview may exhibit a deceptive behaviour because their general intention is to deceive. The behaviour may thus be ambiguous. In these trials the classification for tt responses was always *truth*

and the classification for dd responses was always *deception*. However, in some trials we treated td responses as *truthful responses* and in other trials as *deceptive responses*.

We define: DA as the ‘deception accuracy’, the percentage of deceptive responses classified correctly; TA as the ‘truth accuracy’, the percentage of truthful responses classified correctly; and CA is the overall ‘classification accuracy’, the combined percentage of truthful and deceptive responses classified correctly in their respective categories.

A number of trials were carried out. In each trial the data vectors were split into Training (Tr), Validation (Val) and Testing (Te) sets. Tr was used for ANN weight adjustments and the selection of other neural network parameters. Val was used as a stopping condition and for choosing one ANN from a set of trained ANNs that had different starting seeds. Te was used for final testing. Neither Val nor Te was used to adjust the ANN parameters. .

A correct classification of dd as *deception* corresponds to DA; a correct classification of tt as *truth* corresponds to TA; if a td is treated as *truth* a correct classification corresponds to TA; if a td is treated as *deception* a correct classification corresponds to DA.

Trials A, B and C are initial trials that investigated whether the system could detect deception (A), the effect of classification accuracy as channel numbers were increased (B) and the effect of gender and race (C). Trials D concentrated upon between-subject analyses for one sub-group of participants, European men, for both unplanned and planned responses in order to obtain approximate classification accuracies for previously unseen interviewees.

Trial A: Using Randomised Vectors

In this first type of trial the 688 channel measurement data vectors were randomised into eight training, validation, and testing sets (Tr:Val:Te =6:1:1). Cross-validation was employed to make best use of the data. For each trial, one eighth of the data was retained for testing purposes. The trial was repeated 128 times, each ANN having a different starting seed (8), Tr:Val:Te set (8) and psychological classification (2). When the *td* responses were set to *truth*, the mean DA, TA and CA values for the 8 Te sets were 72%, 61%, and 66% ($SD = 6\%$). When the *td* responses were set to *deception*, the mean DA, TA and CA values were 80%, 78%, and 79% ($SD = 5\%$). The results are for randomised vectors. ANN training has used examples of each person's responses. Vectors in Te are different responses but are for the same group of people.

Trial B: Varying the Number of Channels

In this trial the number of channels was varied. The 688 channel measurement data vectors were repartitioned into three training, validation, and testing sets (Tr:Val:Te=1:1:1). The *td* responses were set to *truth*. The trial was repeated 744 times, each ANN having a different theme combination (31), starting seed (8) and Tr:Val:Te set (3). Each theme was used on its own (5), two themes were used (10 possible combinations), three themes (10 possible combinations), four themes (5 possible combinations) and five themes together (1).

Figure 3 shows the mean Te CA values. Where there are large 95% CI error bars this is because the results are based upon just 3 ANNs chosen by the validation sets. The figure shows that using more channels or data themes causes an increase in CA. Each theme or channel, on its own, gives results close to chance levels. The result that eye gaze alone is a poor indicator of truth/deception, concurs with results reported previously (Baker, Goldstein, and Stern, 1992). Eye closure, head movement

and blushing/blanching, and known data on their own, also give results close to chance levels. However, using more channels or data themes causes an increase in CA, showing that each channel appears to be highly relevant when presented with other channel data. Thus, for this set of channels it is the relationships between the channels that are important and not the individual channels themselves.

Vectors in the testing set are different responses but are for the same group of people. This may be suitable in certain applications. However, in most real-world situations it is desirable that processes related to deception and truth are detected in previously unseen people and that no ‘base-line’ measurements or feedback are required. Therefore, in subsequent trials, Testing contained persons not seen in either Training or Validation.

Trial C: Investigating Gender and Ethnic/ Cultural Differences

This trial investigated the influence of gender and ethnicity/culture in varying deceptive behaviour. Eight Tr:Val:Te sets were initially constructed. There were 15 European men in the data set. For each set Tr/Val contained the responses from 13 European men and different European men (2) were retained for testing. A further three testing sets Te1, Te2 and Te3 were constructed, these containing European women (14), non-European men (5) and non-European women (5). As far as the ANN was concerned each person was a European man. This was done by a manual adjustment of the ‘known data’ part of each response input pattern. There were approximately 20 responses per person. The *td* responses were set to *truth*. The trial was repeated 64 times, each ANN having a different starting seed (8) and Tr:Val:Te set (8). The final set of trained ANNs were tested with Te, Te1, Te2 and Te3.

The mean Te, Te1, Te2 and Te3 CA values are shown in figure 4. The CA for European men is higher than for person types not trained upon. These persons may

exhibit slightly different patterns of behaviour compared to European men. This concurs with literature, which indicates that there are differences between the behaviours of men and women and people of different culture (Bond, 1990; Vrij, 2000). On examining the actual ANN outputs it was found that, in each case, the fall in CA was due to a fall in the number of deceptive responses detected. The system has a truthful bias and is less able at detecting patterns that indicate deception when used with person types it has not been trained upon.

Trial D: Unplanned and Planned Responses of European men

Trial D concentrated upon analyses for unseen European men, for both unplanned and planned responses in order to obtain approximate classification accuracies and to determine whether the results were significantly above chance levels. We used an alpha level of .05 for all statistical tests. Te contained persons not seen in either Tr or Val. The classification of td responses was varied between the sub-trials D1 to D4. Table 4 shows the Deception Accuracy (DA), Truth Accuracy (TA) and the Classification Accuracies (CA) of responses for trials D1 to D4.

European men Trial D1: td Response set to "truth"

Fifteen Tr:Val:Te sets were constructed such that Tr:Val contained the randomised vectors of 14 European men, Te contained the responses from the remaining European man. The trial was repeated 120 times each ANN having a different Tr:Val:Te set (15) and seed (8). The training and testing was such that truthful responses from a deceptive interview, td responses, were classified as "truth".

The testing results in Table 4 for planned interviews show that the classification of truthful (td) responses is similar to truthful (tt) responses. The participant is exhibiting a truthful behaviour for both td and tt responses. For unplanned interviews the classification for truthful (tt) responses is better than truthful

(td) responses. The results suggest that the pattern of behaviour exhibited during the td responses of an unplanned interview may be slightly deceptive even though the actual verbal content is truthful. The participant may *leak* a deceptive pattern of behaviour when they are telling the truth because a participant knows that he or she has just deceived or will have to deceive soon. For the planned interviews the participant knew the questions and question order. The td result indicates less or no leakage.

In training and testing it was assumed that the td patterns were “truth” but the results indicate that in the unplanned interview the td patterns indicate a deceptive behaviour not a truthful behaviour as was expected. The inclusion of such responses in the training set damages the ability of the ANN to learn the patterns that represent a deceptive behaviour because the ANN is incorrectly being told that a deceptive pattern of behaviour is a truthful pattern of behaviour. Therefore the results for deceptive responses are sub-optimal.

European men Trial D2: td Response set to “deception”

The only difference between the trials D1 and D2 was how the truthful responses from a deceptive interview (td responses) were handled during training and testing. In this trial the *td* responses were set to “*deception*”. The testing results in Table 4 for unplanned interviews show that the classification of deceptive (td) responses is similar to deceptive (dd) responses. The participant is exhibiting a deceptive behaviour for both td and dd responses. The results confirm that the pattern of behaviour exhibited during the td responses of an unplanned interview may be slightly deceptive even though the actual verbal content is truthful. For planned interviews the classification for deceptive (dd) responses is better than deceptive (td) responses. It is likely that the td responses from planned interviews thus exhibit a

truthful pattern of behaviour, which again, confirms the results from trial D1. As with trial D1, the results for deceptive responses are sub-optimal because of the inclusion of such responses in the training set. Trial D3 attempts to remedy this problem.

European men Trial D3: td Response set to “deception” in only Unplanned Interviews

This trial was a repeat of D1 and D2 but the classification was such that a td response was set to “deception” when it occurred in an unplanned interview and “truth” when it occurred in a planned interview. The testing results in Table 4 for unplanned interviews show that the classification of deceptive (td) responses is similar to deceptive (dd) responses and that for planned interviews the classification of truthful (td) responses is similar to truthful (tt) responses. The slight increase in CA for unplanned interviews is due to the more correct classification of the td responses. Again, this confirms that in an unplanned deceptive interview a response with a truthful content may offer a deceptive pattern of behaviour.

For planned interviews the overall results are only to chance levels. The planned deceptive (dd) responses appear to be different to the unplanned deceptive (dd) responses because the DA values are very different. One hypothesis that might explain the results would be that the ANN has biased itself towards learning responses from the unplanned interviews. This was addressed in trial D4.

European men Trial D4: Training upon only Unplanned or only Planned Responses

In trial D3 training was upon both planned and unplanned responses. In the first part of trial D4 only the unplanned responses were used for both training and testing. In the second part of trial D4 only the planned responses were used for both training and testing. The treatment of the td responses was as per trial D3, that is

“deception” for unplanned responses and “truth” for planned responses. The data set used in each part of the trial was approximately one half that used in trial D3.

The testing results in table 4 show that for the first part of this trial, the CA for responses from unplanned interviews (74%) is slightly lower than trial D3 (79%) but this may be because the data set is smaller. For the second part of the trial, the CA for responses from planned interviews is slightly higher (62%) than trial D3 (54%). This is still lower than that for unplanned interviews due to the poor classification of deceptive responses (44%). The poor result may be due to a number of reasons. First, only 35% of the responses of the planned data set are deceptive giving the ANN fewer examples to learn. Second, the planned deceptive responses may be more difficult to learn. Trial D2 indicated that planned and unplanned deceptive responses might be different. In unplanned interviews, deceptive participants may be more impulsive and provide similar behaviours to one another. In planned interviews the participant may bring into use strategies learnt over a life-time, such strategies resulting in a greater range of participant behaviour. Third, because a planned truthful interview followed an earlier unplanned deceptive interview there may be some carry-over, e.g. an attempt to conceal previous deception. Thus, it is likely that the differences between planned truthful and planned deceptive responses are less distinct. A larger number of participants used in training will probably provide improved results. Also, a planned truthful interview should not follow an earlier interview where the participant was being deceptive.

European men: Accuracy of Response Classification

Trial D4 is the ‘fairest’ trial because unplanned and planned responses are slightly different and thus training and testing should be done separately. CA for unplanned responses is 74% and for planned responses 62%. The results are likely to

improve with a larger data set, as suggested by the results for unplanned interviews in trial D3.

European men: Accuracy of Interview Classification

For some purposes an interviewer may find a simple, coarse classification of the interview to be sufficient. Specifically, to know if a participant's overall behaviour was truthful or deceptive during the interview. In this work an interview is deemed to be deceptive if three or more responses are deceptive. This criterion and the results determined in D1, D2, D3 and D4 produces the DA, TA and CA values in Table 5. In trial D4 the CA for unplanned interviews is 80% and for planned interviews 61%.

Previous Trials A, B and C

The results from trial D show that the behaviour of participants differs depending upon whether an interview is planned or unplanned. Also, in an unplanned interview the td responses, although having a truthful content, may provide a deceptive behaviour pattern. Thus the training and testing strategies used in trials A, B and C provide CA values that are sub-optimal. The data still supports the hypothesis that as the number of channels increases so does the CA and also that men and women and people of different ethnicity/culture exhibit different patterns of behaviour. Changes to trial A, a within-participant/interview designed trial, such that unplanned interviews from European men are used and the td responses are set to 'deception' gives CA=87% ($p<0.001$). This compares to CA=74% ($p<0.001$) when classifying different European men. The classification rate for the same men but responses from a different unplanned interview is likely to be between 74% and 87%.

Discussion

Multichannel Approach

Telling lies involves control, arousal/felt emotion and cognitive processing (Ekman, 1985). Many different channels may indicate deception; no single channel is the best or most sensitive source and some are more controllable than others (Zuckerman and Driver, 1985). In this work Silent Talker uses a multichannel approach to detect patterns between the channels. The relationship between channels is particularly important, for example in indicating incongruence. Silent Talker can detect behaviours associated with “deception” and as the number of channels increases (Trial B) so does the classification accuracy. The multichannel approach is needed to obtain reasonable accuracy levels and a robust system.

Specialist multichannel pattern classifiers, such as “Unplanned Response European Female classifier” can be created fairly easily. This is useful because different scenarios, interviewer and interviewee types provide different channel patterns (Bond, 1990; Feldman and Rime, 1991; Vrij, 2000). The choice of classifier can be made automatically in-use by the use of artificial intelligence.

Vrij and Mann (2004) suggest that high hit rates could be achieved by employing an objective and systematic lie detection method. Silent Talker satisfies both of these requirements. Further, it does not suffer from fatigue and can rapidly record and analyse many more cues than a human. The authors also state that it “may well be the case that, when controlling their behaviour, liars may ‘over-control’ their behaviour and may exhibit patterns of behaving that will appear planned, rehearsed, and lacking in spontaneity”. Silent Talker is an ideal method of detecting such patterns.

Classification Accuracy

With Silent Talker, the classification accuracies were obtained non-invasively, in near real-time, used many channels, and did not require a base-line test or a highly

trained 'expert'. The classification accuracies depend upon the situation, the people in the data set (number and type) and the channels used (number and type). In most interview situations the responses will be unplanned. In trial D4, where training was upon unplanned interviews of European men, and testing was upon unplanned interviews of different European men, 74% ($p < .001$) of responses and 80% of interviews (12 out of 15, $p = .035$) were classified correctly. The results are significantly above chance levels ($p < .05$).

. The human interviewers classified 6 of the 14 participants, to chance levels ($p = .791$). (The other participant, by choice of language, made it obvious which interview was deceptive.) It may be suggested that the participants in this work were particularly poor liars. The experimental methodology was designed to prevent this. It is also possible that the interviewers were particularly poor at detecting lies. However, they did achieve the levels of detection normally expected (Zuckerman and Driver, 1985). Their mean classification accuracy across all interview pairs was 46%, this being consistent with chance levels ($p = .736$).

Comparison of Classification Accuracy

The analysis by Zuckerman and Driver (1985) of previous deception studies showed that the accuracy of lie detection was between 45% and 60%. Using the same interview procedure as in this work police officers attained 60% accuracy when viewing only hand movements but also given information and feedback (Vrij, 1994). From ten other studies, the best accuracy attained was 70% by students (Vrij, 2000). Police officers also attained 76% (Porter et al. 2000) given information and feedback, but the same speakers may have been used for pre and post training. The accuracies are for interviews not individual responses. The results from the current work

compare favourably with these manual and often-laborious methods that require a trained 'expert'.

Ekman et al. (1991) reports 86% accuracy when analysing participants' smile type and voice pitch when describing a scene truthfully or deceptively. Participants had to describe both horrific and beautiful scenes as being serene. The accuracy quoted is related to the complete unplanned description, not an individual response. The Silent Talker system was almost able to match these results, obtaining 80% for unplanned interviews (86% in trial D3). It would be with the scenario presented in the current study. Despite the limitations placed on detection systems by the use of only two channels, particularly when one, voice pitch, requires a valid baseline test, the use of smile type and voice pitch is of interest to the current study; both channels could be added to Silent Talker, increasing its potential to detect incongruences.

A summary of laboratory-based Polygraph tests reviewed by Vrij (2000) gives the accuracy close to 70%. The results rely upon a valid base-line test. The Polygraph uses only a small number of channels that are indicators of arousal. Given knowledge of the Polygraph, subjects can control their responses. Voice analysis devices also rely upon a valid base-line test and tend to measure arousal. Cestaro and Dollins(1994) gives the accuracy of these devices as close to chance levels. The results from the current work compare favourably with both of these approaches. In this paper, results are reported for full responses and for whole interviews. Classifying short time periods in isolation is more difficult than classifying a whole interview, which can result from a single instance of deception. Accuracies reported in the literature are typically for a whole interview of unspecified length. When undertaking comparisons it is important to consider whether the accuracy is for a short time-period (and what that time is) or for a whole interview.

Limitations and Future Work

Each participant was assigned to perform both a deceptive and truthful interview. Greater realism might have been obtained if the participants had free choice as to which to perform. Motivation levels were low, so we attempted to raise the stakes in the laboratory experiment by introducing lying as an important skill. Nevertheless, we accept that the behaviours being displayed are more comparable to everyday lies than high stake ones. Silent Talker may well be more accurate when trained and validated in high stake situations because deception in such situations is easier to detect (Vrij 2000) . .

The channels that we measured have been investigated by other researchers (Zuckerman and Driver, 1985; Ekman, 1985). Individually they provided only chance level accuracy. We were required to use multiple channels to obtain reasonable accuracy levels. We hypothesised that this was because the channel interrelationships were important not the individual channels.

. The inclusion of channels that offer more indicative behaviours, such as finger movements (Vrij, 1994; Vrij, 2000), is likely to further improve the accuracy rates .However, the over-reliance on any given channel could prove to be counter-productive. As with the Polygraph, a subject could learn how to manipulate(or hide) a particular channel that is known to be important.

Regarding data collection, a truthful interview may be biased by prior behaviour if it follows a deceptive interview; a subject might appear deceptive because they are covering up the fact that they lied in the previous interview. Consequently, planned truthful interviews need to be handled differently, for example by having two truthful interviews.

The starting point for future work, is the collection of a larger data set. As more examples of behaviours are seen by the system, the classification upon previously unseen participants is improved. Specialist multichannel pattern classifiers, for example ‘European Female Classifier’, may also offer improved accuracies. For practical applications, real-life video data will need to be collected for training and testing purposes along with the known ground truth as determined by other means. Interviewer, stakes and physical setting could be varied in order to examine exhibited behaviours in these different scenarios.

The addition of more channels (Vrij, 1994; Vrij, 2000), will probably improve the classification accuracy. Channels could be nonverbal and auditory cues (e.g. finger/hand, foot, torso movement, voice pitch), speech content related (e.g. number of ‘self references’) or some other cue, such as brain wave activity.

A person’s nonverbal behaviour can alter significantly over a full response. Initial trials using short fixed time-period data suggest the possibility of “charting” a person’s behaviour over an interview. Multiple cameras can also facilitate channel extraction from a number of people at once, so that individual behaviours and interactions between people can be analysed. A possible application of this would be monitoring behaviour at airport check-ins. Using a machine questioner in the training, testing and in-use phases would permit the system to be automated.. This would allow staff to concentrate on those passengers more likely to be of concern. Data is currently being collected for a possible medical application and applications in business and education. Obviously, to use Silent Talker in such applications, the data needs to be processed directly from the camera, i.e. ‘on the fly’.

Conclusion

This paper presents a new ANN-based psychological profiling system, Silent Talker. The system was tested by attempting to detect behaviours related to deception, however, many other applications are apparent. The advantages of Silent Talker are that the system is non-invasive, operates in real-time, does not rely upon a small number of channels/cues and, as an ANN-based system, provides the long-sought-after objectivity required in profiling. The system allows for the exchange and/or addition of channels. For each application, many output classifications and situational variants can be examined. Different classifiers can be trained for different groups of people and different situations in order to fine tune the system. Machines that rely upon one, two, three or a limited number of channels can easily be affected by some factor other than the one being measured or by the subject's conscious control of those channels. Because Silent Talker operates upon multiple channels of nonverbal behaviour it is likely to be a better detector of the psychology of a subject

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Table 1

Channel Descriptions

Theme	Channel description
Known data	female/male, European/Non-European, unplanned/planned (3)
Face/head	movement upwards, movement downwards, vertical movement,
Movement	movement left, movement right, horizontal movement, scale (forward/back), movement forwards, movement backwards (9)
Eye gaze	left eye looking to the left, to the right, moving side to side right eye looking to the left, to the right, moving side to side (6)
Eye closure	left eye closed, left eye blink, right eye closed, right eye blink (4)
Blushing/	increase in face redness, decrease in face redness (2)
Blanching	

Table 2

Number of objects and non-objects used for ANN training/testing and the Classification Accuracies (CA) for the testing sets.

Object	No. object	No. non object	Testing set CA (%)		
			Object	Non object	Total
Face	1560	7800	96	99	98
L eye	4680	18720	80	96	92
L eyebrow	1560	4680	82	93	89
Nose	1560	4680	94	98	96

Table 3

Number of target patterns and non-target patterns used for ANN training/testing and the Classification Accuracies (CA) for the testing sets.

Target pattern type	No. target pattern	No. non-target Pattern	Testing set CA (%)		
			Target pattern	Non-target pattern	Total
Left eye f closed	2004	7356	76	89	86
Left eye hf closed	2994	6366	82	89	87
Left eye f right	1038	8322	67	95	92
Left eye hf right	2622	6738	79	91	83
Left eye f left	1038	8322	62	97	93
Left eye hf left	2658	6702	71	88	88

Note. f=fully, hf = half/fully

Table 4

Deception Accuracy (DA), Truth Accuracy (TA), and total Classification Accuracy (CA), in percent, for 142 unplanned (U) and 138 planned (P) responses.

Trial	Training (Tr) Variation		Te Data	Response Testing (Te)(%)					
	Tr Data	td		dd	td	tt	CA		
				DA	DA	TA	TA		
D1	U & P	“truthful”	U	48		42	82	64 ^{***}	65 ^{***}
			P	36		75	84	66 ^{***}	
D2	U & P	“deceptive”	U	80	79		68	74 ^{***}	62 ^{***}
			P	56	30		49	49 ^a	
D3	U & P	“deceptive” if U	U	88	92		68	79 ^{***}	67 ^{***}
			P	11		75	77	54 ^b	
D4 (1)	U	“deceptive”	U	76	83		69	74 ^{***}	68 ^{***}
D4 (2)	P	“truthful”	P	44		65	73	62 ^c	
Weight				0.7	0.3	0.3	1	2	4

Note. ^{***} p < .001 ^ap = .932 ^bp = .349 ^cp = .005

Table 5

Deception Accuracy (DA), Truth Accuracy (TA), and total Classification Accuracy (CA), in percent, for 15 unplanned (U) and 15 planned (P) whole interviews.

Trial	Training (Tr) Variation		Interview Testing (Te)				
	Tr Data	td	Te Data	DA	TA	CA	
				%	%	% (<i>p</i>)	% (<i>p</i>)
D1	U & P	“truthful”	U	75	71	73 (.118)	70 (.043)
			P	43	89	66 (.302)	
D2	U & P	“deceptive”	U	100	57	79 (.035)	67 (.099)
			P	71	38	55 (1.000)	
D3	U & P	“deceptive” if U	U	100	71	86 (.007)	63 (.200)
			P	14	63	39 (.607)	
D4 (1)	U	“deceptive”	U	71	88	80 (.035)	70 (.043)
D4 (2)	P	“truthful”	P	50	71	61 (.607)	

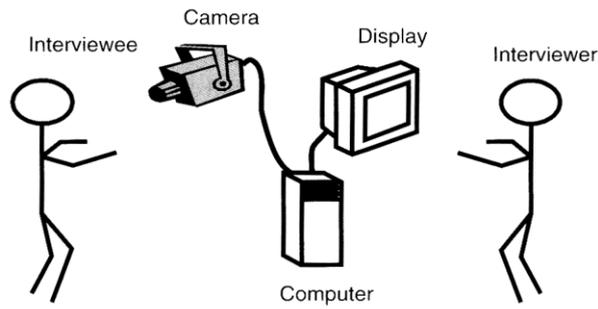


Figure 1. Trained system

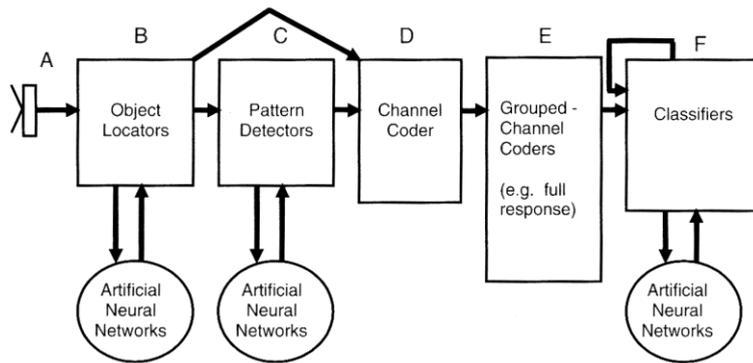


Figure 2. System diagram

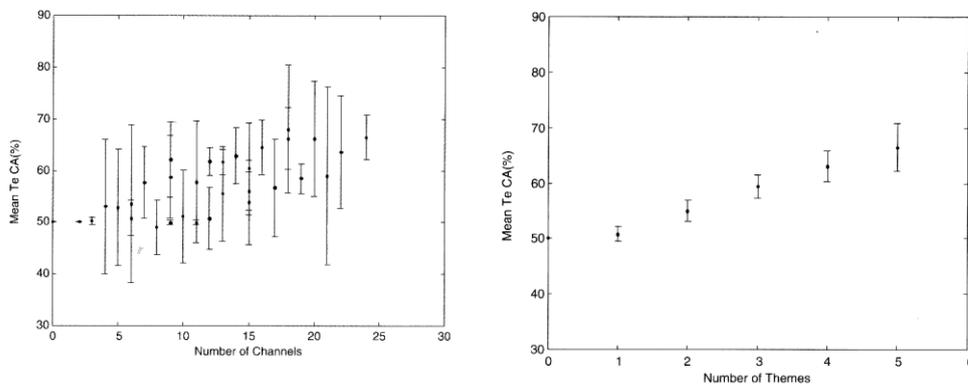


Figure 3. Mean Classification Accuracy (95% CI) in percent for previously unseen responses as the number of channels and the number of themes varies

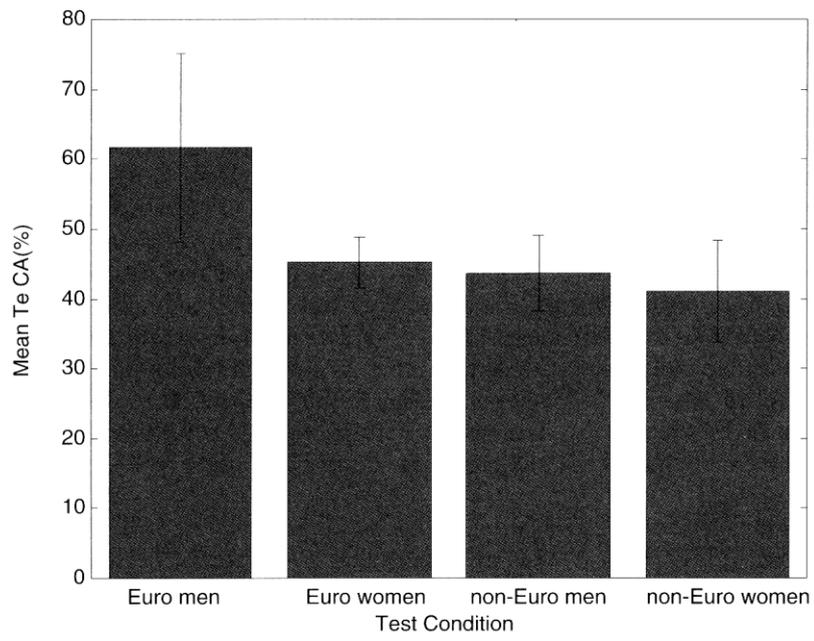


Figure 4. Mean Classification Accuracy (95% CI) in percent for responses of previously unseen people for ANNs trained upon European men